

ASA10080-97 – Generic Datasheet

Shape Memory Alloy Closed-Loop Auto-Focus Actuator

CONFIDENTIAL and PROPRIETARY PRELIMINARY

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1 Overview

ASA10080-97 is a closed loop autofocus actuator that can be integrated into mobile phone camera systems. The actuation force is provided by a Shape Memory Alloy (SMA) wire. The closed loop control is performed by the embedded driver IC and Hall sensor BU64748GWZ produced by Rohm.

This document provides a general description of the actuator as well as standard performance and reliability specifications. These specifications can be modified to meet customer's requirements after agreement between both parties.

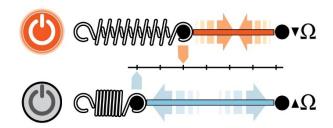
1.1 ASA10080-97 General Specifications

Items	Specifications
Dimension (X, Y, Z) ⁽¹⁾	10 mm x 10 mm x 4 mm
Barrel Diameter	Φ8 mm
Actuator weight (without lens)	≤ 0.40g
DC resistance of SMA wire	25 ± 1Ω
Position Feedback	Hall Sensor
Operation temperature	-30°C~70°C
Storage Environment	-40°C~35°C 10~90% RH
Max clamping force for active alignment	15N (1.5kgf)

1.2 Actuation Principle

When current flows into the SMA wire, the SMA wire starts to shrink and overcomes the bias spring force. When the current is cut off, the bias spring force overcomes the SMA wire force, as shown in Figure 1.

Figure 1: SMA Wire Operation Principle



⁽¹⁾ Detailed dimension please see the drawing in section 4.



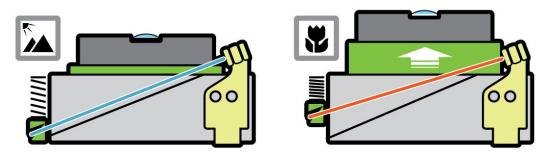


Figure 2: SMA Actuator Principle

Figure 2 shows the SMA wire on the actuator. When the current is cut off, the Lens stays in the INF position. When the current flows into the SMA wire, the Lens moves toward the Macro position. The Lens position is controlled by the Magnet on the Lens Carrier and the hall sensor integrated driver IC.

1.3 Closed Loop Control

Rohm combined driver IC and Hall sensor (BU64748GWZ) is embedded into the autofocus actuator. This means that no driver IC is required onto the CMOS sensor FPC/PCB.

An initialization file is saved into the baseband with all the required driver IC settings (eg: PID settings for closed loop). When the camera is switched on, the baseband transfers all settings to the driver IC register.

Optional: Different PID settings can be used for forward and backward motions and increase the actuator performance. To enable this option, the baseband has to transfer the correct PID settings to the driver IC each time that the motion direction is changed.

Features		Characteristics
Built in Hall Sensor		
Driver	H-Bridge Output Curre	nt (Max 150mA)
2-Wire Serial Interface	I ² C address	0xECh (W), 0xEDh (R)
Fully Digital Equalizer		
Gain Adjustment for Hall Sensor		
Thermal Shut Down (TSD), Under		
Voltage Locked Out (UVLO)		
Built in small Capacity	10 Byte (for User)	
Ferroelectric RAM (FeRAM)	8 Byte (Calibration)	
Supply Voltage	2.4 to 3.8V	

Table 2: BU64748GWZ Features



1.4 Typical Application Circuit

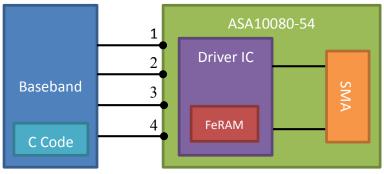


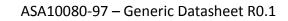
Figure 3: ASA10080-97 Typical Application Circuit

Electrical connection to the driver IC is made through 4 pads (pad 1 to pad 4). The pads are defined in Table 3. A FeRAM non-volatile memory is embedded into the driver IC. The Hall sensor calibration is executed in ASG factory and stored into the FeRAM.

A C code program provided by the driver IC supplier should be implemented into the baseband. When the camera is turned ON, the C code program retrieves the calibration data from the FeRAM through I²C communication and then updates the Driver IC registers.

Table 3: ASA10080-97 Pads definition

Pin	Label	Remarks
1	SDA	Data of I ² C Interface
2	SCL	Clock of I ² C Interface
3	GND	Ground
4	VCC	Power Input : Typical 2.8V





2 ASA10080-97 Performance Specifications

For all performance measurements, the actuator motion is along the Z axis in the upward direction. The following specifications are given for standard environment conditions:

- Temperature: 25 ± 2°C
- Relative Humidity: 50 ± 20% RH

Table 4: ASA10080-97 Performance Specifications

Items		Specifications	
Usable Stroke		≥ 350µm	
Operation power consumption (operating current, I _{RMS} < 56mA)		<150mW ⁽²⁾	
Max power	SMA wire (at 350um stroke)	≤ 220mW	
consumption	Driver IC	≤ 30mW	
Actuator moving time step size: 30um		< 20ms	
Dynamic Tilt (from 0um to 350um stroke)		< 8 minutes	
Hysteresis		≤ 10µm	
Accuracy		± 5um	
Posture difference		< 15µm	
Peak Audible noise (1cm from Actuator)		<20dBA (background noise only)	

⁽²⁾ In closed-loop control.



3 Reliability Tests Specifications

The test quantity is 20 pieces for each item. The actuator should meet the general specifications and performance specifications after reliability test.

Thermal Tests	Specifications		
Cold Storage	 (1) Storage Temperature: -40±2°C (2) Temperature Ramp: 2°C/min (3) Storage Time: 144hrs (4) Temperature Cycle Count: 1 cycle (5) Actuation Signal: None (6) Actuation Period: NA (7) Actuation Count: NA (7) Actuation Count: NA (8) Lens Weight: NA (9) Testing Temp. & Humidity: 25±5°C, 50±20% RH 	(D _o) 25 	
Cold Operation	 (1) Operation Temperature: -30±2°C (2) Temperature Ramp: 2°C/min (3) Operation Time: 144hrs (4) Temperature Cycle Count: 1 cycle (5) Actuation Signal: square wave 0um → 350um (6) Actuation Period: 15sec@0um, 15s@350um (7) Actuation Count: 17280 (8) Lens Weight: 0.18g (9) Testing Temp. & Humidity: 25±5°C, 50±20% RH 	(D ₀) 25 	

Table 5: Thermal Reliability Tests Specifications



Thermal Tests	Specifications		
Dry Heat Storage	 (1) Storage Temperature: 85±2°C (2) Temperature Ramp: 2°C/min (3) Storage Time: 144hrs (4) Temperature Cycle Count: 1 cycle (5) Actuation Signal: None (6) Actuation Period: NA (7) Actuation Count: NA (8) Lens Weight: NA (9) Testing Temp. & Humidity: 25±5°C, 50±20% RH 	Lemberature (°) Hereitaria (°	
Dry Heat Operation	 (1) Storage Temperature: 70±2°C (2) Temperature Ramp: 2°C/min (3) Operation Time: 144hrs (4) Temperature Cycle Count: 1 cycle (5) Actuation Signal: square wave 0um → 350um (6) Actuation Period: 15sec@0um, 15s@350um (7) Actuation Count: 17280 (8) Lens Weight: 0.18g (9) Testing Temp. & Humidity: 25±5°C, 50±20% RH 	Lemberatrice (°C) Test Test Time (h) 144 144	



Thermal Tests	CONEIDENSPEC	fications
Temperature & Humidity Storage	 (1) Storage Temp. & Humidity: 60±2°C, 90±5% RH (2) Temperature Ramp: 2°C/min (3) Storage Time: 144hrs (4) Temperature Cycle Count: 1 cycle (5) Actuation Signal: None (6) Actuation Period: NA (7) Actuation Count: NA (8) Lens Weight : NA (9) Testing Temp. & Humidity: 25±5°C, 50±20% RH 	(C) HW(K) (H) (C) (C) (C) (C) (C) (C) (C) (C) (C) (C
Thermal Shock (Storage)	 (1) High Storage Temperature: 85±2°C Low Storage Temperature: -40±2°C (2) Temperature Ramp: <3min (3) Temperature Holding Time: 30min (4) Temperature Cycle Count: 300 cycles (1hr/cycle) (5) Actuation Signal: None (6) Actuation Period: NA (7) Actuation Count: NA (8) Lens Weight: NA (9) Testing Temp. & Humidity: 25±5°C, 50±20% RH 	$\begin{array}{c} 1 \text{ Cycle} \\ \hline \begin{array}{c} 1 \text{ Cycle} \\ \hline \begin{array}{c} 299 \text{ Cycles} \\ \hline \end{array} \\ \hline \begin{array}{c} 1 \text{ Cycle} \\ \hline \end{array} \\ \hline \begin{array}{c} 299 \text{ Cycles} \\ \hline \end{array} $ \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \end{array} \\ \hline \\ \hline \\ \hline \end{array} \\ \hline \\ \hline \\ \hline \\ \hline \end{array} \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \\



Table 6: Mechanical Reliability Tests Specifications		
Mechanical Tests	Specifications	
Vibration Test	(1) 10-55Hz sweep sine wave	
	(2) Direction: X, Y, Z directions	
	(3) Sweep time (10~50~10): 2min	
	(4) Amplitude 2mm (p-p)	
	(5) Time: 30min each direction	
Life Test	(1) Operation Temp. & Humidity: 25±5°C, 50±20% RH	
	(2) Actuation Signal: square wave 0um \rightarrow 350um	
	(3) Actuation Period: 0.1s@0um, 0.1s@350um	
	(4) Actuation Count: 100,000	
	(5) Lens weight: 0.18g	
	(6) Testing Temp. & Humidity: 25±5°C, 50±20% RH	
Drop Test	(1) Testing Temp. & Humidity: 25±5°C, 50±20% RH	
	(2) Drop Height: 1.6m	
	(3) Drop Count: 6 Drops per cycle (6 faces)	
	(4) Cycle Count: 3 Cycles	
	(5) Lens weight: 0.18g	
	(6) Fixture weight: 148g	
	(7) Drop Surface: steel	
	(1) Drop Height: 1m	
	(2) Rotation Speed: 8rpm	
Tumble Test (Random Free Fall)	(3) Rotation Count: 200 rotations (400 drops)	
	(4) Lens weight: 0.18g	
	(5) Fixture Weight: 148g	
	(6) Drop Surface: steel	
	(1) Drop Height: 8cm	
	(2) Drop Directions: Top, bottom, side	
Repeat Low Level free fall test (with lens unit)	(3) Cycle Count: 10000 Cycles for top and bottom	
	2500 Cycles for side	
	(4) Lens weight: 0.18g	
	(5) Fixture weight: 148g	
	(6) Drop Surface: steel	

Table 6: Mechanical Reliability Tests Specifications



Mechanical Tests	Specifications
Pressure Test	(1) Pressure: 5kg
	(2) Holding time: 15sec
	(3) Direction: Normal to Top surface
Shield can pull out test	(1) Pull out force ≥ 2kg
	(2) Equipment: Force Gauge

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4 ASA10080-97 Dimension and Appearance Specifications

4.1 Dimensions Specifications

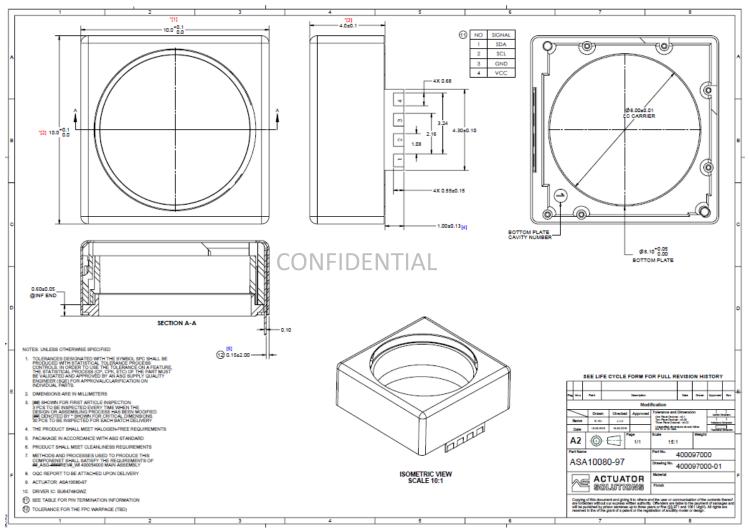


Figure 4: ASA10080-97 2D Drawing



4.2 Appearance Specifications

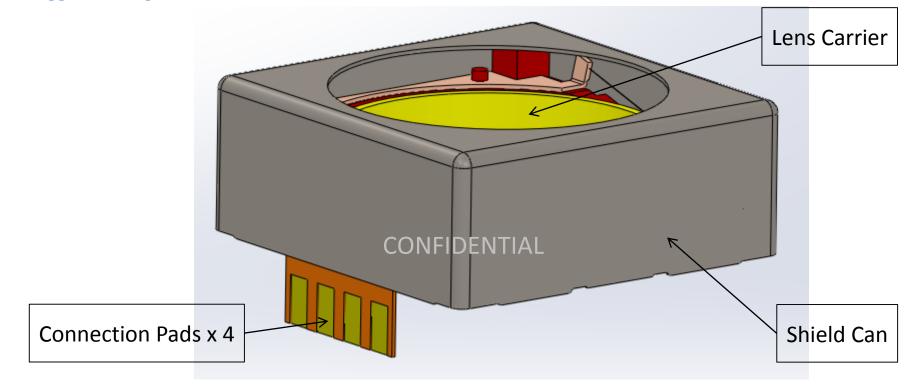


Figure 5: ASA10080-97 Actuator – 3D View



Table 7: Appearance Specifications

ltem	Appearance Specification
Outer Appearance	Free of burrs > 0.05mm on side walls
	Free of burrs > 0.02mm on top and bottom faces
	Free of particles larger than 0.02mm
	Free of Rust, crack, discolor, stain, glue and solder residue
	Free of scratches larger than 0.05mm width
Lens Carrier Screw	Free of cracks
	Free of burrs > 0.020mm
Flexure	No discolor or rust
	No floating
FPC Pad	Free of oxidation
	Free of glue
Serial Number Label	No warp or tilt
	Clear to read

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